SEAGUARD[®] RCM Recording Current Meter



The new SEAGUARD[®] RCM series replaces the industry standard RCM 9 and RCM 11 series. It has been completely redesigned from bottom up and employs modern technology in the datalogger section and in the different sensor solutions.

The SEAGUARD[®] architecture is based on a general datalogger unit and a set of autonomous smart sensors. The datalogger and the smart sensors are interfaced by means of a reliable CANbus interface(AiCaP), using XML for plug and play capabilities. During power-up, each of the sensors that are connected to the bus will report their capabilities and specifications to the datalogger. The datalogger then assembles the information and provides the user with the possibility to configure the instrument based on the present nodes. The solution provides for great flexibility in both use and design of the different elements within the system.

The autonomous sensor topology also gives the sensor designer flexibility and opportunities where each sensor type may be optimized with regard to its operation, each sensor may now provide several parameters without increasing the total system load.

Data storage takes place on a Secure Digital (SD) card. The current capacity for this card type is up to 4GBytes, is more than adequate for most applications.



SEAGUARD® Recording Current Meter

The SEAGUARD[®] RCM series is a completely new generation of current meters based on the SEAGUARD[®] datalogger platform and the ZPulse[™] Doppler Current Sensor¹. Modern computer technology combined with advanced digital signal processing provides accurate and detailed measurements with almost unlimited resolution. Optional parameters are available through a new range of smart sensors that include temperature, pressure, conductivity,oxygen, wave and tide. The new SEAGUARD[®] RCM series come in 300m, 2000m and 6000m depth ranges.

SEAGUARD[®] RCM advantages:

- Large storage capacity on SD card
- Broadband ZPulse[™] multi-frequency technology reduces power consumption and improves quality
- Down to 2 second recording interval
- Low current drain
- Smart sensor topology based on a reliable semi-high speed CANbus interface (AiCaP)
- Up to 4 Analog sensor input (0-5V)
- Windows CE based datalogger with TFT based color touch panel for local configuration
- SEAGUARD Studio visualization software
- For use in sea and fresh water
- Real-Time XML Output (optional)

Patent Pending

The SEAGUARD[®] also has an built-in power calculator which gives an etsimated deployment lenght bases on selected interval, battery type and current drain information, obtained from each smart sensor.

Sensor Capability

The SEAGUARD[®] RCM comes standard with the ZPulse[™] multifrequency Doppler current sensor. The new current sensor comprises acoustic pulses of several frequency components to lower the statistical variance in the Doppler shift estimate. The advantage of this is reduced statistical error with fewer pings, providing increased sampling speed and lower power consumption. The new Doppler Current Sensor also incorporates a robust fully electronic compass and a tilt sensor.

The SEAGUARD[®] RCM may also be delivered with new smart sensor solutions for Temperature, Pressure, Conductivity and Oxygen. All sensors have increased resolution compared with the older models. The temperature sensor also has decreased settling time to utilize the increased sampling speed provided by the SEAGUARD[®] platform. There is also an analog Turbidity Sensor available for direct connection on the top end plate.

Specifications

Top-end Plate capability:	1	rs can be fitted onto the , of which 4 can be s (0-5V)
Recording System:	Data Storage	
Storage Capacity:	$\geq 4GB$	
Battery:		
Alkaline 3988:		minal 12.5Ah; 20W
	down to 6V at	t 4°C)
or Lithium 4002:	7V, 30Ah	
Recording Interval:		ending on the node for each instrument
Recording settings:	Fixed interval	
0 0		equence setting
Protocol:		us based protocol
Depth Capacity:	300m/2000m/	6000m
Platform Dimensions:		
300m version (SW):	H: 356mm O	D: 139mm
2000m version (IW):	H: 352mm O	D: 140mm
6000m version (DW):	H: 368mm O	D: 143mm
External Materials:		
300m version:	PET, Titanium, Stainless Steel 316,	
		322 polyurethane
2000/6000m version:	Stainless steel	316, Titanium, OSNI
		g DT322 polyurethane
Weight:	In Air	In Water
300m version (SW):	7.6 kg	2.0 kg
2000m version (IW):	14.8 kg	8.5 kg
6000m version (DW):	15.7 kg	10.5 kg
Supply Voltage:	6–14 Volts	
Operating Temperature:	-5 to +50°C	

Optional Accessories and Sensors

Optional Accessories:	Carry handle 4132,4032,3965	Wave and T
Mooring frame:	In-line 4044 ²⁾ /3824A	Pressure:
	Bottom 3448R	
	Protecting Rods 3783	
	Sub-surface floats 2211,2212	Wave:
Battery:	Internal Lithium 4002	
5	Internal Alkaline 3988	Pressure Ser
	Internal Battery Shell 4513	Resolution
	Electrical terminal 4810,4618	Accuracy
	AC/DC adapter with cable 4497	4117A Ra
	Real Time licence and collector 4715	4117B Ra
	Offline Configuration 4811	4117C Ra
	Analog cable/license 4564/4802	4117D Ra
	Maintenance Kit 3813/3813A	4117E Ra
	Tools kit 3986A	4117F Ra
	Vane Plate 3781,3681	Turbidity Se
	Hardcopy Documentation	0-5V Anal
Optional Sensors:		4112 R
Temperature Sensor 4060		4112A R
Range:	-4-36°C (32-96.8°F) ³⁾	4112B R
Resolution:	0.001°C (0.0018°F)	4112C R
Accuracy:	±0.03°C (0.054°F)	Oxygen Opt
Response Time 63%):	< 2 seconds	Measuremen
Conductivity Sensor 4319	/4319IW	Resolution
Range:	0-7.5 S/m	
Resolution:	0.0002 S/m	Accuracy:
Accuracy		
4319 A/AIW:	±0.005 S/m	Response 7
4319 B/BIW:	±0.0018 S/m	
Response Time:	<3s ⁵)	

1) Based on 300 pings

2) In-line Mooring Frame 4044: breaking strength 800 kg

3) Extended range available on request.

4) Available on request

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	2000	
ZPulse [™] Doppler Current	t Sensor (DCS) Specifications	
Current Speed:	(Vector averaged)	
Range:	0-300 cm/s	
Resolution:	0.1 mm/s	
Mean Accuracy:	$\pm 0.15 \text{ cm/s}$	
Relative:	\pm 1% of reading	
Statistic variance (std)	0.3 cm/s (ZPulse mode),	
	0.45 cm/s ¹⁾	
Current Direction:		
Range:	$0-360^{\circ}$ magnetic	
Resolution:	0.01°	
Accuracy:	$\pm 5^{\circ}$ for 0-15° tilt	
	±7.5° for 15-35° tilt	
Tilt Circuitry:		
Range:	0-35°	
Resolution:	0.01°	
Accuracy:	±1.5°	
Compass Circuitry:		
Resolution:	0.01°	
Accuracy:	±3°	
Acoustics:		
Frequency:	1.9 to 2.0 MHz	
Power:	25 Watts in 1ms pulses	
Beam angle (main lobe):	2°	
Installation distance:		
From surface:	0.75m	
From bottom:	0.5m	
Accessories Included:	SEAGUARD Studio	
	SD card: 512 MB	
	Alkaline Battery 3988	

Tide Sensor 4648A Range: 0-400kPa (0-58psia) Resolution : <0,002% FSO Accuracy: ±0,04% FSO Sampling rate: 2Hz, 4Hz 256,512,1024,2048 Number of samples: ensor 4117 <0.002% FSO on: $\pm 0.04^{\circ}$ FSO *y*: 0 - 1000kPa $(0 - 145 \text{ psia})^{4)}$ ange: 0 - 4000kPa (0 - 580 psia) ange: 0 - 10000kPa (0 - 1450 psia)⁴⁾ ange: 0 - 20000kPa (0 - 2900 psia) lange: 0 - 40000kPa $(0 - 5800 \text{ psia})^{4}$ ange: 0-60000kPa (0-8700 psia) ange: Sensor 4112 alog Output Range: 0-25 FTU Range: 0-125 FTU 0-500 Range: FTU 0-2000 FTU6) Range: otode 4330 **O2-Concentration Air Saturation** 0 - 150% ent Range: $0-500 \ \mu M$ n: < 1 µM 0.4~%: <8 µM or 5%⁷⁾ <5 % whichever is greater Time (63%): 4330F (with fast response foil) <8 sec 4330 (with standard foil) <25 sec

Documentation on CD

5) Dependent on flow through cell bore

6) Sensor is non-linear above 750 FTU

7) Requires salinity compensation for salinity < 1mS/cm

8) Within calibrated range 0-120%

Illustrations and Descriptions

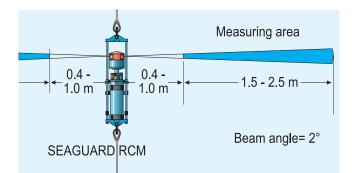
The ZPulse[™] Doppler Current Sensor (DCS) is the standard sensor on the SEAGUARD[®] RCM. The sensor outputs Absolute Current Speed and Direction, Speed in east and north direction, Ping count, and extensive readout of quality control parameters such as Single-ping Standard deviation, Heading, Tilt in X- and Y-direction, and Signal Strength.

The SEAGUARD[®] RCM utilizes the wellknown Doppler Shift principle as basis for its measurements.



Note!

If application requires breaking strength of more than 800 kg, mount the SEA-GUARD® RCM SW in in-line mooring frame 3824A. Remember to change the handles.



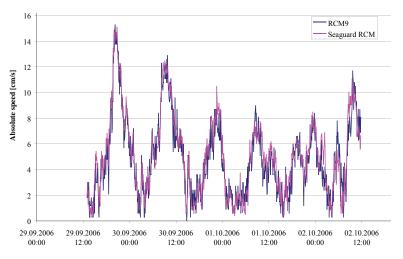
Four transducers transmit short pulses (pings) of acoustic energy along narrow beams (600, 300, 150, or 50 pings in each recording interval). The same transducers receive backscattered signals from scatteres that are present in the beams, which are used for calculation of the current speed and direction.

The scattering particles are normally plankton, gas bubbles, organisms and particles stemming from man-made activity.

To minimize the effect of marine fouling and local turbulence, the ZPulse[™] DCS starts measuring the horizontal current in an area of 0.4 to 1.0 meter from the instrument, see figure above.

Comparing SEAGUARD® RCM with RCM 9

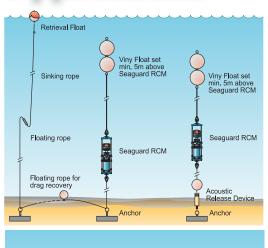
The SEAGUARD[®] RCM has been tested together with a RCM 9 to compare the measurement results. The deployment was performed during a weekend in a fjord outside Bergen. The graph below shows the absolute speed of both instruments. Pink graph is representing the SEAGUARD[®] RCM, while blue is representing the RCM 9. The SEAGUARD[®] was in this test set to transmit 150 ping during each recording interval, while the RCM 9 was set to transmit 300 ping. Although the SEAGUARD[®] only transmitted half as many pings compared to the RCM 9, the two instruments gave very similar results. Lower ping count reduces power consumption.

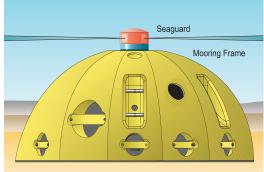


Comparision between data measured by a SEAGUARD® RCM (pink) and a RCM 9 (blue). The graph is showing absolute speed measured in a fjord outside Bergen, Norway.

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Applications





SEAGUARD Studio

With SEAGUARD Studio you can:

- Import deployment data collected by the SEAGUARD® • RCM from a SD card.
- Display configuration setting used in the depoyment.
- Display listed data.
- Possible to show data from several instruments at the same time for comparative studies.
- Export data to Matlab.
- Export data to ASCII text files.
- Print or export graphs in different formats.
- Copy graphs to the clipboard for inclusion into other programs such as Word. Excel or similar.
- Save edited sessions.
- Calculate virtual parameters.

AADI Real-Time

The data message from the instrument is in XML format A user application can access the AADI Real-Time Collector over the Internet or Intranet. Each user application will experience an individual connection to the instrument data due to an queue management system in the collector. One license per SEAGUARD[®] instrument serves multiple user applications. Including AADI Real-Time Collector, AADI Real-Time Viewer, Style Sheets and example application (See B163)

5851 BERGEN, NORWAY TEL. +47 55 60 48 00 FAX. +47 55 60 48 01

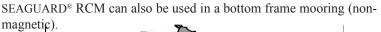
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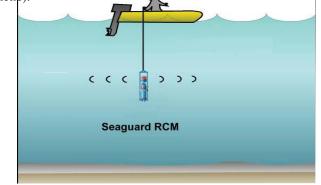
http://www.aadi.no e-mail: info@aadi.no

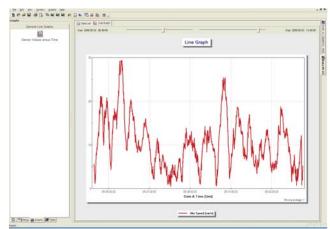


The most common way to use the SEAGUARD® RCM is in an inline mooring configuration. As it operates under a tilt up to 35° from vertical, it has a variety of in-line mooring applications by use of surface buoy or sub surface buoy. The instrument is installed in a mooring frame that allows easy installation and removal of the instrument without disassembly of the mooring line.

Drop line is conveniently done due to its compact design, low drag force and easy handling. The instrument can be lowered into the sea from a small boat using a simple winch. Data can be stored internally and read after retrieval.







Example of SEAGUARD Studio presenting absolute speed data measured with a SEAGUARD® RCM.

Offline Configuration

The Seaguard Offline Configuration is a PC application used to create and modify configuration files for the SEA-GUARD[®]. The configuration files can be imported to one or multiple SEAGUARD® instruments using a compatible memory card (SDcard).(See TD 275).

Representative's Stamp